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TARGETED PROPERTY-BASED TESTING

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Outline

- Random Property-Based Testing
- Motivation
- Targeted Property-Based Testing

- Case Studies
- Concluding Remarks



Property-Based Testing

- High-level, semi-automatic, black-box testing technique.
- Testing user-specified properties of the SUT.
- Examples:
 - QuickCheck (Haskell)
 - ScalaCheck (Scala)
 - PropEr (Erlang)
 - ...



PropEr

A QuickCheck-Inspired Property-Based Testing Tool for Erlang

Random Property-Based Testing

- PBT tool provides:
 - Random generators for basic types
 - Language to write more complex generators
- PBT tool automatically tests these properties
 - Generate wide range of random inputs
 - Run the SUT with these inputs
 - Check if the properties hold



Random Property-Based Testing

Generator

`prop_list_reverse() ->`

```
?FORALL(L, proper_types:list(integer()),  
lists:reverse(lists:reverse(L)) == L).
```

Property should hold for all `L`

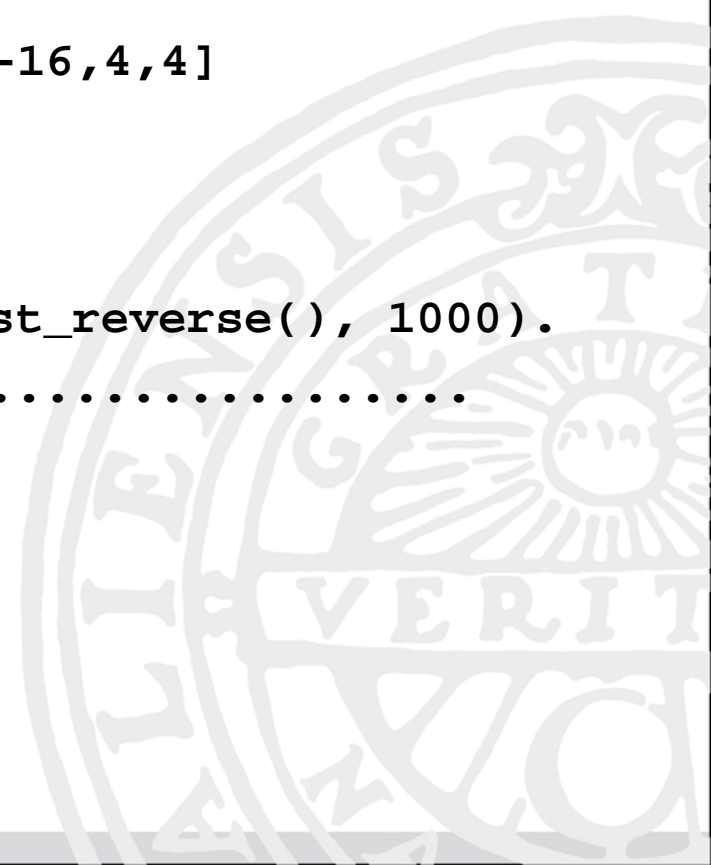
General Property



Random Property-Based Testing

```
L = []  
L = [2]  
L = [-5,-1,-8,1]  
L = [16,3,-23]  
L = [38,29,-28,12,-11,-3,-28,-6,9,-16,4,4]  
...
```

```
1> proper:quickcheck(example:prop_list_reverse(), 1000).  
..... 1000 dots .....  
OK: Passed 1000 test(s).
```





Graph Generator

graph(N) ->

```
Vs = lists:seq(1, N),
```

```
?LET(Es, proper_types:list(edge(Vs)),
```

```
{Vs, lists:usort(Es)}).
```

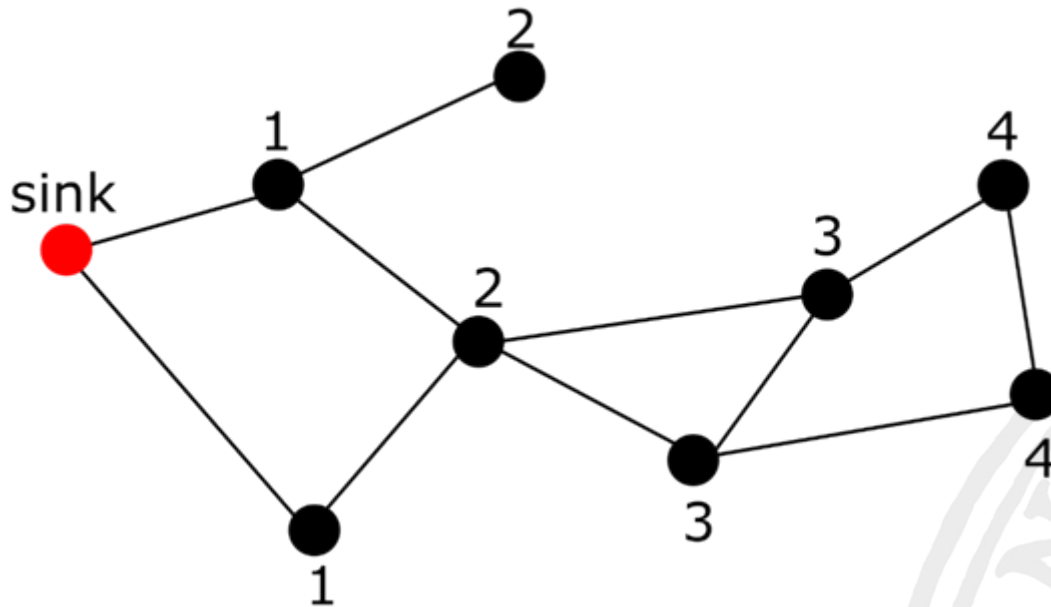
edge(Vs) ->

```
?SUCHTHAT({V1, V2}, {oneof(Vs), oneof(Vs)},
```

```
V1 < V2).
```



Distance From Sink



On this graph, the maximum distance to sink is 4.

Is there a network with 42 nodes where the maximum distance to the sink > 21 ?



Distance From Sink

```
prop_length( ) ->  
  ?FORALL(G, graph(42),  
    begin  
      L = lists:max(distance_from_sink(G)),  
      L < 21  
    end).
```

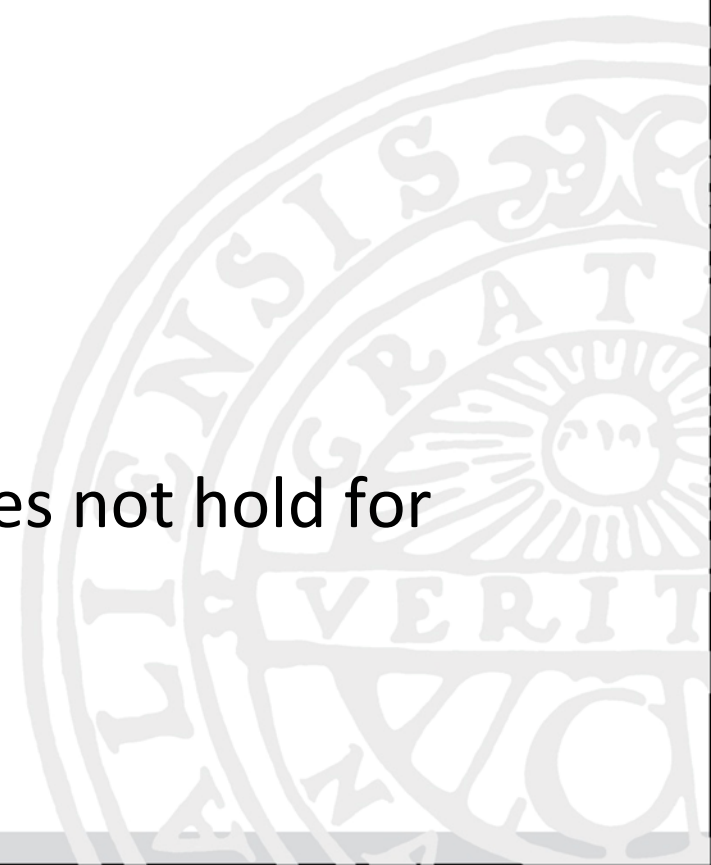


Distance From Sink

```
1> proper:quickcheck(example:prop_length(), 100000).  
..... 100000 dots .....  
OK: Passed 100000 test(s).
```

Same result for 1000 repetitions.

But we know that the property does not hold for some graphs.





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Possible Solutions

- Write more involved generators?
- Guide input generation?





Possible Solutions

- ~~Write more involved generators?~~
- **Guide input generation!**
 - Using a search strategy.



Targeted Property-Based Testing

```
prop_length( ) ->  
  ?FORALL( G, graph( 42 ),  
    begin  
      L = lists:max(distance_from_sink( G ))  
      L < 21  
    end ).
```

- Use a search strategy to find a `G` that falsifies the property.
- Observe the relationship between `G` and `L`.



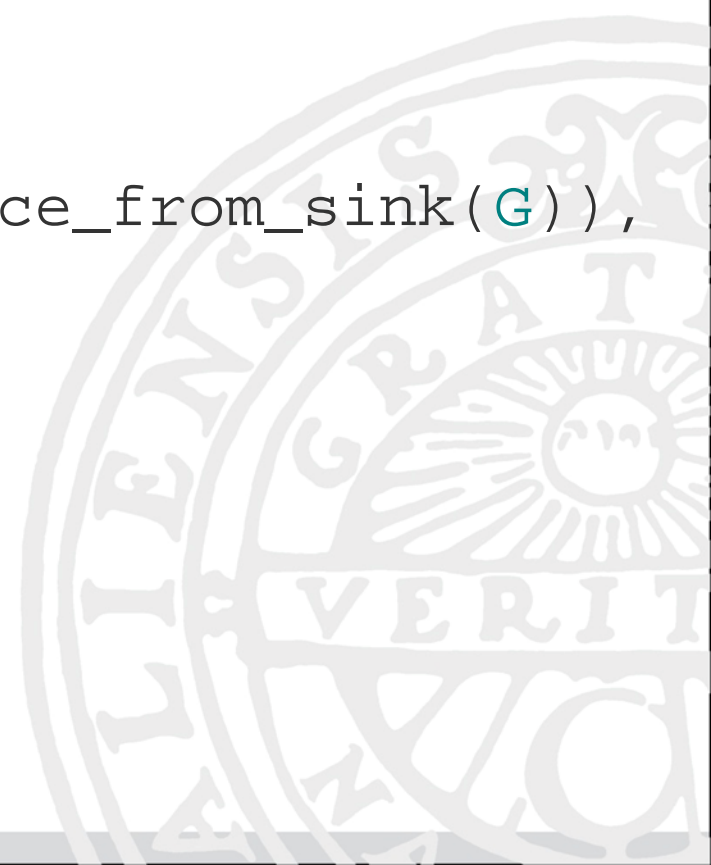
Targeted Property-Based Testing

- Combine Search Techniques with Property-Based Testing.
- Guide input generation towards input with high probability of failing.
- Gather information during test execution in form of **utility values (UVs)**.
- UVs capture how close input came to falsifying a property.



Targeted Property-Based Testing

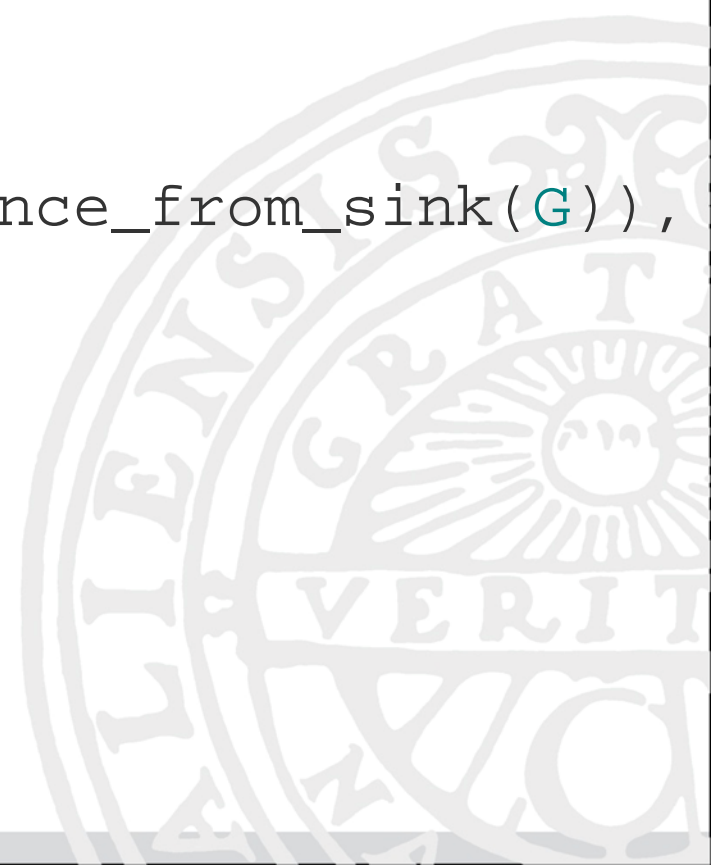
```
prop_length_hc( ) ->  
  ?FORALL(G, graph(42),  
    begin  
      L = lists:max(distance_from_sink(G)),  
      L < 21  
    end) .
```





Targeted Property-Based Testing

```
prop_length_hc() ->  
  ?FORALL(G, graph(42),  
    begin  
      Utility UV = lists:max(distance_from_sink(G)),  
      Values  UV < 21  
    end).
```





Targeted Property-Based Testing

```
prop_length_hc() ->  
  ?FORALL(G, graph(42),  
    begin  
      Utility  
      Values  UV = lists:max(distance_from_sink(G)),  
              ?MAXIMIZE(UV),  
              UV < 21  
    end).
```

Search Target



Targeted Property-Based Testing

```
prop_length_hc() ->
```

```
  ?FORALL(G, ?TARGET(graph(42)),
```

Generator the
strategy controls

```
    begin
```

Utility
Values

```
      UV = lists:max(distance_from_sink(G),
```

```
        ?MAXIMIZE(UV),
```

```
        UV < 21
```

```
      end).
```

Search
Target



Targeted Property-Based Testing

```
prop_length_hc() ->
```

```
?TARGET_STRATEGY(hill_climbing,
```

```
?FORALL(G, ?TARGET(graph(42))),
```

```
begin
```

```
UV = lists:max(distance_from_sink(G)),
```

```
?MAXIMIZE(UV),
```

```
UV < 21
```

```
end)) .
```

Search
Strategy

Generator the
strategy controls

Utility
Values

Search
Target



Targeted Property-Based Testing

```
prop_length_hc() ->  
  ?TARGET_STRATEGY(hill_climbing,  
  ?FORALL(G, ?TARGET(graph_hc(42))  
  begin  
    UV = lists:max(distance_from_sink(G)),  
    ?MAXIMIZE(UV),  
    UV < 21  
  end)) .
```

Search Strategy

Generator the strategy controls

Utility Values

Search Target

Now `prop_length_hc` fails after 17,666 tests (on average).

Targeted Property-Based Testing

- Hill Climbing requires a neighborhood function
 - which, currently, needs to be supplied by the programmer
 - remove and add some random edges from/to the graph

Depends on the search strategy

- Hill Climbing can get stuck in local optima
 - Simulated Annealing is a better strategy



Targeted Property-Based Testing

```
prop_Target ( ) ->  
  ?TARGET_STRATEGY ( SearchStrategy ,  
    ?FORALL ( Input , ?TARGET ( Params ) ,  
      begin  
        UV = SUT:run ( Input ) ,  
        ?MAXIMIZE ( UV ) ,  
        UV < Threshold  
      end ) ) .
```

Search Strategy

Generator the strategy controls

Utility Values

Search Target

Case Study 1

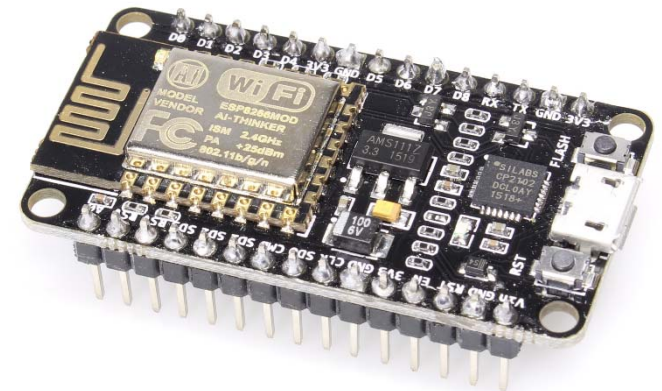
Setup:

- Sensor network
- Random distribution of UDB server and client nodes
- Client node periodically sends messages to server node

Test:

- Has X-MAC for any network a
duty-cycle $> 25\%$?

(duty-cycle ::= % time the radio is on)





Case Study 1

Random PBT

- Average amount of tests: **1188**
- Average time per tests: 23.5s
- **Mean Time to Failure: 7h46m**

Targeted PBT

- Average amount of tests: **200**
- Average time per tests: 40.6s
- **Mean Time to Failure : 2h12m**





Case Study 3

$$\frac{i(pc) = \text{Noop}}{\boxed{pc} \mid \boxed{s} \mid \boxed{m} \Rightarrow \boxed{pc+1} \mid \boxed{s} \mid \boxed{m}} \quad (\text{NOOP})$$

$$\frac{i(pc) = \text{Push } v}{\boxed{pc} \mid \boxed{s} \mid \boxed{m} \Rightarrow \boxed{pc+1} \mid \boxed{v : s} \mid \boxed{m}} \quad (\text{PUSH})$$

$$\frac{i(pc) = \text{Pop}}{\boxed{pc} \mid \boxed{v : s} \mid \boxed{m} \Rightarrow \boxed{pc+1} \mid \boxed{s} \mid \boxed{m}} \quad (\text{POP})$$

- Definitions for an abstract machine.
- Test: Do these definitions fulfill a certain security criteria?

(Noninterference)

Cătălin Hrițcu et al. "Testing noninterference, quickly." *Journal of Functional Programming*, 26 (2016).

Case Study 3

Random PBT

- **Naive:** generate random programs
- **ByExec:** generate program step-by-step one instruction a time; new instruction should not crash program

	Random PBT	
	Naive	ByExec
ADD	2234,08ms	312,97ms
LOAD	324028,34ms	987,91ms
STORE A	<i>timeout</i>	4668,04ms

Case Study 3

Targeted PBT

- **List**: programs are a list of instructions; using the built-in list generator for Simulated Annealing
- **ByExec**: neighbor of a program is a program with one more instruction

	Random PBT		Targeted PBT	
	Naive	ByExec	List	ByExec
ADD	2234,08	312,97	319,86	68,49
LOAD	324028,34	987,91	287,23	135,52
STORE A	–	4668,04	1388,09	263,94



Case Study 3

hand written; ca. 30 lines of additional code

	PBT	ByExec	Target List	ByExec
ADD	2234,08	312,97	319,86	68,49
LOAD	324028,34	987,91	287,23	135,52
STORE A	–	4668,04	1388,09	263,94

1 line of code!



Concluding Remarks

- Framework for Targeted Property-Based Testing.
- High-level expressive language for specifying properties.
- Compatible with random PBT.
- Two built-in strategies: hill climbing + simulated annealing.
- Infrastructure for additional search strategies.
- Fully integrated into PropEr.



PropEr

A QuickCheck-Inspired Property-Based Testing Tool for Erlang